

**In the Specification:**

**Please amend the specification as follows:**

**Page 3, sixth paragraph:**

A three-axle ball and socket joint in a robot (Fig. 5) comprises a joint socket and a joint ball.  
The joint socket 1 encloses the ball of the joint (not shown) with a space that comprises approximately a half of a sphere or less (Fig. 1). A housing 2 shaped to accommodate a bearing means 3 is located within socket 1. Bearing means 3 includes a bearing surface 10 engaged by a surface 11 of joint ball 9 as shown in Fig. 4(a).